

Manual



Interface Adapter USM21A

Edition 03/2021

26868253/EN





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1 General information

1.1 About this documentation

The documentation at hand is the original.

This documentation is an integral part of the product. The documentation is intended for all employees who perform work on the product.

Make sure this documentation is accessible and legible. Ensure that persons responsible for the systems and their operation as well as persons who work on the product independently have read through the documentation carefully and understood it. If you are unclear about any of the information in this documentation or if you require further information, contact SEW-EURODRIVE.

1.2 Other applicable documentation

Always use the latest edition of the documentation and the software.

The SEW-EURODRIVE website (www.sew-eurodrive.com) provides a wide selection of documents for download in various languages. If required, you can also order printed and bound copies of the documentation from SEW-EURODRIVE.

1.3 Rights to claim under limited warranty

Read the information in this documentation. This is essential for fault-free operation and fulfillment of any rights to claim under limited warranty. Read the documentation before you start working with the product.

1.4 Product names and trademarks

The brands and product names in this documentation are trademarks or registered trademarks of their respective titleholders.

1.5 Decimal separator in numerical values

In this document, a period is used to indicate the decimal separator. Example: 30.5 kg

1.6 Copyright notice

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2 Safety notes

2.1 **Preliminary information**

The following general safety notes serve the purpose of preventing injury to persons and damage to property. They primarily apply to the use of products described in this documentation. If you use additional components, also observe the relevant warning and safety notes.

2.2 Target group

Software specialist Any work with the software may only be performed by a specialist with suitable training. A specialist in this context is someone who has the following qualifications:

- Appropriate training
- Knowledge of this documentation and other applicable documentation
- SEW-EURODRIVE recommends additional training for products that are operated using this software.

2.3 Designated use

The interface adapter USM21A is designed for connecting an engineering PC with a USB interface to the diagnostic slot of a unit from SEW-EURODRIVE.

2.4 Network security and access protection

A bus system makes it possible to adapt electronic drive technology components to the particulars of the machinery within wide limits. There is a risk that a change of parameters that cannot be detected externally may result in unexpected but not uncontrolled system behavior and may have a negative impact on operational safety, system availability, or data security.

Ensure that unauthorized access is prevented, especially with respect to Ethernetbased networked systems and engineering interfaces.

Use IT-specific safety standards to increase access protection to the ports. For a port overview, refer to the respective technical data of the device in use.



3 Device structure

3.1 Interface adapter USM21A

With the interface adapter USM21A, it is possible to connect an engineering PC with a USB interface to the diagnostic slot of a device from SEW-EURODRIVE. The connection is made with a device-specific connection cable. Refer to chapter "Available connection cables" ($\rightarrow \blacksquare$ 7) for information on which cable you need for your device. The connection to the engineering PC and the power supply is made via a USB type B socket. The data is transferred according to the USB 2.0 standard. Operation on a USB 3.0 device is also possible. The matching connection cable is included in the delivery.

The adapter communicates with the device via RJ10 socket. Depending on the supported interface standard of the diagnostic interface, the interface adapter is connected to the RS485 interface or the system bus interface (CAN bus) of the device. The version and baud rate of the interface used is defined in the MOVITOOLS[®] MotionStudio engineering software, in MOVISUITE[®] standard or LT Shell depending on the device type and the requirements. For more information, refer to chapter "Available connection cables" (\rightarrow \square 7).

The interface converter and the device communicate only point-to-point, and the termination of the RS485 and the CAN bus is permanently installed.

The interface adapter is equipped with a status display for the bus and an error display.

The following figure shows the interface adapter, its connections and displays.



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- [1] USB socket type B
- [2] "Bus status display" ($\rightarrow \square 6$)
- [3] RJ10 socket
- [4] "Interface adapter status display" ($\rightarrow \blacksquare 7$)

3.1.1 Bus status display

LED	Meaning
Off	No driver is activated for the interface adapter.





LED	Meaning
Lights up green	Driver activated, but still no communication between the engineering PC and the device.
(RS485) or	Possible causes for the interface adapter remaining in this status:
	The connection cable to the device is not connected properly or is defective.
	The baud rate setting on the device is incorrect.
	The device has no operating voltage.
	 The device address is outside the address range set for the device in the MOVITOOLS[®] MotionStudio project.
Flashes green (RS485) or blue (CAN)	Bus communication is active. Data is being exchanged between the engineering PC and the device.

3.1.2 Interface adapter status display

LED	Meaning
Off	Normal operating state.
Lights up red	There was an error in the interface adapter.

3.2 Scope of delivery

The scope of delivery includes the following components:

Component	Part number
USM21A interface adapter	
USB connection cable (type A to type B)	28231449
Interface cable (RJ10 to RJ10)	

3.3 Replacement cables

The following replacement cables are available for the interface adapter:

Replacement cable	Part number
USB connection cable (type A to type B)	08186804
Interface cable (RJ10 to RJ10)	08146993

3.4 Available connection cables

A matching connection cable is required to connect the interface adapter to the device. A RJ10 to RJ10 connection cable is included in the delivery and is available as a replacement cable if required ($\rightarrow \blacksquare$ 7). You can purchase additional connection cables from SEW-EURODRIVE. The following table shows the connection cables required for your device.



The following software versions are required as a minimum:

- MOVISUITE® standard: as specified in the table
- MOVITOOLS® MotionStudio: V6.30
- LT Shell V4: V3.1.0.1

Device	Plug connector on the device	Part number of the connection cable	Engineering software ¹⁾
DRC electronic motor	RJ10	08146993	MT
	D-sub, 9-pin	18123864	MT
MOVIDRIVE [®] modular with CiA402 device profile (EtherCAT [®] master without mailbox gateway function)	RJ10	08146993	MS V2.0 (SP9)
MOVIDRIVE [®] system with CiA402 device profile (EtherCAT [®] master without mailbox gateway function)	RJ10	08146993	MS V2.0 (SP9)
MOVIDRIVE [®] technology	D-sub, 9-pin	18123864	MS V2.1 (SP10)
MOVIDRIVE [®] MDXB	RJ10	08146993	MT
MOVIFIT [®] MC/FC/SC	RJ10	08146993	MT
MOVIGEAR [®] B	RJ10	08146993	MT
MOVIGEAR [®] performance	M12, 5-pin, A-coded (X4141)	28147111	MS V2.0 (SP9)
MOVIGEAR [®] performance	M12, 5-pin, B-coded (X4142)	28139038	MS V2.0 (SP9)
MOVIGEAR [®] performance	RJ10 ²⁾	08146993	MS V2.0 (SP9)
MOVIMOT [®] advanced	M12, 5-pin, B-coded (X4142)	28139038	MS V2.2
MOVIMOT [®] advanced	RJ10	08146993	MS V2.2
MOVIMOT [®] flexible	M12, 5-pin, A-coded (X4141)	28147111	MS V2.2
MOVIMOT [®] flexible	M12, 5-pin, B-coded (X4142)	28139038	MS V2.2
MOVIMOT [®] flexible	RJ10	08146993	MS V2.2
MOVIMOT [®] flexible (MMF3 only)	D-sub, 9-pin	18123864	MS V2.2
MOVIMOT [®] performance	RJ10	08146993	MS V2.1 (SP10)
MOVIMOT [®] performance	M12, 5-pin, B-coded (X4142)	28139038	MS V2.1 (SP10)
MOVIMOT [®] MMD	RJ10	08146993	MT
MOVISAFE [®] DCSB	RJ10	08146993	MT
MOVISAFE® UCSB	RJ10	08146993	MT
MOVITRAC [®] advanced	D-sub, 9-pin via CDM11A diagnostic module, part number 28265092	18123864	MS V2.20
MOVITRAC [®] B	RJ10	08146993	MT
MOVITRAC [®] LTE-B+	RJ45	18243681	LT



Device	Plug connector on the device	Part number of the connection cable	Engineering software ¹⁾
MOVITRAC [®] LTE-B+	RJ45	28118677	MT
MOVITRAC [®] LTP-B	RJ45	18243681	LT
MOVITRAC [®] LTP-B	RJ45	28118677	MT

1) LT = LT Shell V4, MS = MOVISUITE® standard, MT = MOVITOOLS® MotionStudio

2) Plug connector on the PCB, the device must be opened.





4 Startup

4.1 Requirements

The required version of the engineering software depends on the device and the bus used. For more details, refer to chapter "Available connection cables" ($\rightarrow \square$ 7).

4.2 Configuration in MOVITOOLS[®] MotionStudio

The interface adapter is connected either to the RS485 interface or the CAN bus interface, depending on the device type. It is necessary to configure the corresponding communication connection.

- "Setting up RS485 communication" ($\rightarrow \square$ 10)
- "Setting up CAN bus communication" ($\rightarrow \blacksquare$ 11)

4.2.1 Setting up RS485 communication

Proceed as follows:

- ✓ You have installed the required version of the engineering software on the engineering PC. For information on the required version, refer to "Requirements" (→
 10).
- ✓ You have not started an engineering software on the engineering PC.
- 1. Start MOVITOOLS® MotionStudio.
- To configure the communication connection, click [Configure communication connections] in the toolbar.
 - ⇒ This opens the "Configure communication connections" window.
- 3. Select the "Serial" entry from the drop-down list of a communication connection that is not yet in use.
- 4. Click the [Edit] button of the communication connection.
 - \Rightarrow The "Serial" window opens.

ħ	Ethernet Activate Ethercat: No Activate SMLP: Yes		Carlinate
È	SBus Baud rate: 500 KB		Activate
P	Serial COM port: 3, Baud rate: AUT	10	Activate Edit
	v		Activate
/OVITOOLS®-ł	fotionStudio	OK	Cancel



5. In the "COM port" drop-down list, select the port of the engineering PC to which the interface adapter is connected.

Serial			×
	(3) Ser	ial	
Basic settings	Advanced settings		
COM port: Baud rate:	4 (USM21A RS485) AUTO	▼ ▼ (Default	AUTO)
MOVITOOLS®-Mot	onStudio	ОК	Cancel

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- 6. Click [OK].
 - ⇒ This opens the "Configure communication connections" window.
- 7. Click [OK].
- 8. Perform a network scan.

4.2.2 Setting up CAN bus communication

Proceed as follows:

- You have installed the required version of the engineering software on the engineering PC. For information on the required version, refer to "Requirements" (→
 10).
- \checkmark You have not started an engineering software on the engineering PC.
- 1. Start MOVITOOLS® MotionStudio.
- To configure the communication connection, click [Configure communication connections] in the toolbar.
 - ⇒ This opens the "Configure communication connections" window.
- 3. Select the "SBus" entry from the drop-down list of a communication connection that is not yet in use.





- 4. Click the [Edit] button of the communication connection.
 - \Rightarrow The "SBus" window opens.

Configure communication connections	
	C Activate
SBus Baud rate: 500 KB	✓ Activate Edit
3	✓ Activate Edit
	Activate
MOVITOOLS®-MotionStudio	OK Cancel

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5. Select the value "500 KB" from the "Baud rate" selection list.

	(2) SI	Bus	_
Basic settings	Advanced settings		
Baud rate:	500 KB	▼ (De	efault: 500 KB)
MOVITOOLS®-Moti	onStudio	ОК	Cancel

- 6. Click [OK].
 - ⇒ This opens the "Configure communication connections" window.
- 7. Click [OK].
- 8. Perform a network scan.

Special feature MOVITRAC[®] LT..

• Do not select a control signal source for a MOVITRAC[®] LTE-B+ that uses CANopen because this would prevent the inverters from being scanned.

MOVITRAC® LTE B+-Parameter\Parameter				
P-01 Maximum speed	[Hz]	50		
P-02 Minimum speed	[Hz]	0		
P-03 Acceleration ramp time	[s]	5.00		
P-04 Deceleration ramp time	[s]	5.00		
P-05 Stop mode		0: Power failure = continuation of operation/normal stop = ramp P-04	$\overline{}$	
P-06 Energy-saving function		OFF	\sim	
P-07 Rated motor voltage	M	230		
P-08 Rated motor current	[A]	1.6		
P-09 Rated motor frequency	[Hz]	50		
P-10 Rated motor speed	[rpm]	0		
P-11 Boost	[%]	3		
P-12 Control source		0 Teminal mode	\sim	
P-14 Extended parameter access		0 Terminal mode		
P-15 Digital input function selection		2 Keypad mode bipolar 2 SPus utik integration		
P-16 Analog input 1 format	M	4 SBus with filedbus ramp		
P-17 PWM switching frequency	[kHz]	6 Modbus RTU with internal ramp		
P-18 User relay output function selection		8 C NOpen with internal ramp		
P-19 Limit value for relay/analog output	[%]	19 P l controller mode 10 Pl controller with addition of Al1		
P-20 Fixed setpoint speed 1	[Hz]	11 Slave mode	-	
P.91 Eived extension encod 9	11-1		_	

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• Do not select a control signal source for a MOVITRAC[®] LTP-B that uses CANopen because this would prevent the inverters from being scanned.

MOVITRAC® LTP B-Parameter\Overview of parameter groups \P1 - I	Basic pa	irameters
P1-01 Maximum speed	[Hz]	50
P1-02 Minimum speed	[Hz]	0
P1-03 Acceleration ramp time	[s]	5.00
P1-04 Deceleration ramp time	[s]	5.00
P1-05 Stop mode		Stop ramp 🗸
P1-06 Energy saving function (only for ASM)		OFF ~
P1-07 Rated motor voltage	М	230
P1-08 Rated motor current	[A]	4.3
P1-09 Rated motor frequency	[Hz]	50
P1-10 Rated motor speed	[rpm]	0
P1-11 Boost	[%]	2.5
P1-12 Control signal source		Teminal mode 🗸
P1-14 Extended parameter access		Terminal mode Keynad mode forwards
P1-15 Digital input function selection		Keypad mode forwards and reverse
P1-16 Motor type		Slave mode
P1-17 LTX module I/O function selection		CANOI en
P1-18 Motor thermistor selection (only with LTX option)		Multimotion

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4.3 Configuration in MOVISUITE[®] standard

Engineering tasks for components from the MOVI-C[®] modular automation system from SEW-EURODRIVE are performed using the MOVISUITE[®] standard engineering software. USM21A interface adapters are also configured in MOVISUITE[®] standard.

Proceed as follows:

- ✓ You have installed the required version of the engineering software on the engineering PC. For information on the required version, refer to "Requirements" (→
 10).
- \checkmark You have not started an engineering software on the engineering PC.
- 1. Start MOVISUITE[®] standard.
- 2. Click [From network scan].

Start		
New project	Last opened projects	Tools
Planning		Scope
From network scan	Always start with last project	Manual mode
From Workbench		
Open project		
Open		
M Import		
Quick access		
Startup		
Duplication		
- Diagnostics		SEW
O Unit replacement		Driving the world

- \Rightarrow The "Communication..." window opens.
- 3. Click [USB].



- 4. Activate the "Scan" slide switch.
- 5. Click [Apply] to start scanning.

Projects			
		USB	
		Scan settings Scan USB adapters	Basic settings Timeout
Network type	Scan	C Scan	250 ms
Ethernet EtherCAT®/SBusPLUS	Ø	Connected USB adapters USM21A 2038.3536.4834.5708.002D.0028	
USB	Q	Update adapters	
		Apply	Cancel

4.4 Configuration in LT Shell

The engineering tasks for MOVITRAC[®] LTE-B+ and MOVITRAC[®] LTP-B units are performed using the LT Shell software. The USM21A interface adapter is also configured in LT Shell.

Proceed as follows:

- ✓ You have installed the required version of the engineering software on the engineering PC. For information on the required version, refer to "Requirements" (→
 10).
- ✓ You have not started an engineering software on the engineering PC.



1. Start LT Shell.

⇒	Th op	ne bens.		n	nain						window
		IT Shell V4						_		×	
		File Tools Parameters Help)					Drive Fi	rmware: V	1.26	
	[1]-		Group			8					
		Cottline Mode	ID	Description	Value		Range	Default	Visible		
		230V 1~ 0.75kW	P1-01	Maximum Frequency / Speed Limit	50.0 Hz		0.0 250.0	50.0 Hz	v		
		01 Drive Description	P1-02	Minimum Frequency / Speed Limit	0.0 Hz		0.0 50.0 H	0.0 Hz	1		
			P1-03	Acceleration Ramp Time	5.0 s		0.00 600 s	5.0 s	√		
			P1-04	Deceleration Ramp Time	5.0 s		0.00 600 s	5.0 s	-		
			P1-05	Stop Mode Select	0: Ramp to Stop	-		0: Ramp to Stop	1		
			P1-06	Energy Optimiser	0: Disable	-		0: Disable	1		
			P1-07	Motor Rated Voltage	230 V		0, 20 250	230 V	1		
			P1-08	Motor Rated Current	4.3 A		0.4 4.3 A	4.3 A	1		
			P1-09	Motor Rated Frequency	50 Hz		25 500 Hz	50 Hz	√		
			P1-10	Motor Rated Speed	0 rpm		0, 250 30(0 rpm	1		
			P1-11	V/F Mode Voltage Boost	2.5 %		Auto, 0 30	2.5 %	-		
		Add Virtual Drive	P1-12	Primary Command Source Select	0: Terminal Mode	•		0: Terminal Mo	1		
		Scan Drive Network	P1-13	Trip Log	No Fault (no-Fit) No Fault (no-Fit)		0 0	0	1		
		Real-Time Edit Mode	P1-14	Extended Menu Access Code	0		0 30000	0	1		
		Network Scan Limit: 8 🔻	P1-15	Digital Inputs Function Select	1: [Stop/Run] [Fwd/Rev]	-		1: [Stop/Run] [F	1	-	
		Selected Communication Device	e: Wired Se	erial Interface (RS485/RS232) (COM3)						

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- 2. To configure the communication connection, click [1] in the toolbar.
 - ⇒ The "Communication setting" window opens.

Communication Settings	×
Select the connection type	Wired Serial Interface (RS485/RS232) 🔹
Select a serial port	(COM10) USM21A RS485 -
	Show All Serial Ports
	Refresh
Connect	Cancel

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- Select "Wired serial interface (RS485/RS232)" from the "Select connection type" drop-down list.
- 4. In the "Select COM port" drop-down list, select the port of the engineering PC to which the interface adapter is connected.
- 5. Click the [Connect] button.
 - ⇒ The "Communication setting" window closes.
- 6. Perform a network scan.

5 Service

5.1 Waste disposal

Dispose of the product and all parts separately in accordance with their material structure and the national regulations. Put the product through a recycling process or contact a specialist waste disposal company. If possible, divide the product into the following categories:

- Iron, steel or cast iron
- Stainless steel
- Magnets
- Aluminum
- Copper
- Electronic parts
- Plastics

The following materials are hazardous to health and the environment. These materials must be collected and disposed of separately.

Oil and grease

Collect used oil and grease separately according to type. Ensure that the used oil is not mixed with solvent. Dispose of used oil and grease correctly.

- Screens
- Capacitors

Waste disposal according to WEEE Directive 2012/19/EU



This product and its accessories may fall within the scope of the country-specific application of the WEEE Directive. Dispose of the product and its accessories according to the national regulations of your country.

For further information, contact the responsible SEW-EURODRIVE branch or an authorized partner of SEW-EURODRIVE.



6 Technical data

6.1 Markings

The USM21A interface adapter complies with the following directives and regulations:

Mark	Meaning
CC	CE mark to state compliance with the following European guidelines:
עכ	EMC Directive 2014/30/EU
	RoHS Directive 2011/65/EU
50)	RoHS Directive (R estriction o f H azardous S ubstances) of the People's Republic of China to confirm compliance with the regulations of the ACPEIP (A dministration on the C on- trol of P ollution caused by E letronic Information P roducts)

6.2 General

General technical data					
Part number	28231449				
Interference immunity	Meets requirements of EN 61800-3				
Ambient temperature	0 to 40 °C				
Storage temperature	-25 °C to +70 °C according to EN 60721-3-3, class 3K3				
Degree of protection	IP20 in accordance with EN 60529				
Interfaces	RJ10 socket (device connection)				
	USB socket type B (PC connection)				
Mass	200 g				
Dimensions (L × W × H)	92.5 mm × 43 mm × 25 mm				

6.3 Environmental conditions

Climatic conditions	 Extended storage: EN 60721-3-1 class 1K2 temperature -25 °C to +70 °C
	 Transport: EN 60721-3-2 class 2K3 temperature -25 °C to +70 °C
	 Operation (fixed installation, weatherproof): EN 60721-3-3 class 3K3 tempera- ture 0 °C to +60 °C
Chemically active substances	Extended storage: EN 60721-3-1 class 1C2
	Transport: EN 60721-3-2 class 2C2
	 Operation (fixed installation, weatherproof): EN 60721-3-3 class 3C2
Mechanically ac-	Extended storage: EN 60721-3-3 class 1S1
tive substances	Transport: EN 60721-3-3 class 2S1
	Operation (fixed installation, weatherproof): EN 60721-3-3 class 3S1



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